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function candidate for autonomous nonlinear systems of the ____ Chapter 3 Fundamentals of Lyapunov Theory 15 Applied Nonlinear Control Nguyen Tan Tien - 2002.3 ____ form (3.2), namely, $V = f^T f$. The basic idea of the method is function for this system.

Slotine & Li, Applied Nonlinear Control | Pearson

Analysis and Control " (Asada and Slotine, Wiley, 1986), and " Applied Nonlinear Control " (Slotine and Li, Prentice-Hall, 1991) and is one of the most cited researcher in both systems science and robotics. He was a member of the French National Science Council from 1997 to 2002, and a member of Singapore ' s

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Applied Nonlinear Control: Jean-Jacques Slotine, Massachusetts Institute of Technology. Weiping Li, Massachusetts Institute of Technology

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