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perceiving and modeling
environment, localizing and building
maps, planning paths and making
decisions, and controlling the
vehicles within limit time for real-time
purposes.

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The target audience of the book is researchers, professionals and graduate students interested in a broad scientific field that includes not only basic principles, such as signal-

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recognition, but also targeted fields
of application, such as Intelligent
Transportation Systems (ITS) and,
more specifically, Intelligent Vehicles
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