

Discrete Sliding Mode Control For Robust Tracking Of Time

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In , a discrete-time sliding mode controller was proposed for higher order plus delay time processes. In this paper, the main contribution is to develop a discrete-time sliding mode control approach, which can globally stabilize all states, including those which are indirectly actuated through the nonlinear coupling, for a small quadrotor UAV.

Adaptive Neural Sliding Mode Control in Discrete Time for ...

This paper proposes a disturbance observer-based discrete sliding-mode control scheme with the variable sampling rate control for the marine diesel engine speed control in the presence system uncertainties and disturbances. Initially, a sliding-mode controller based on the fast power reaching law is employed, which has a good dynamic quality of the arrival stage and can suppress chattering.

Discrete Sliding Mode Control for Hypersonic Cruise Missile

A new systematic design procedure to synchronize continuous master-slave Lorenz chaotic systems is proposed by using a discrete sliding mode control (DSMC). In contrast to the previous works, the design of DSMC can be simplified and only a single controller is needed to realize chaos synchronization.

Discrete-time sliding mode control for a class of ...

A modified discrete-time sliding surface is proposed to derive the discrete-time sliding mode control algorithms. The algorithm is further extended for the random fractional delay with single packet loss and multiple packet loss situations.

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Discrete-Time Sliding Mode Control for Networked Control ...

The proposed control structure is based on neuro-adaptive sliding mode control to adjust dynamics variations of the SCARA robot. The sliding control is included to ensure that the discrete-time neural control can improve the stable closed loop system to be immune to the parameters variations.

Discrete Sliding Mode Control For

Discrete-time sliding mode control is the obvious transformation from the continuous time sliding mode control for the real-time application. Like continuous time sliding mode control, DTSMC is also easy to design and also well-suited for implementation. 3. Control problem formulation.

Sliding mode control - Wikipedia

Discrete-Time Sliding Mode Control for Nonlinear Systems with Unmatched Uncertainties and Uncertain Control Vector," to appear in the . ASME JOURNAL OF DYNAMIC SYSTEMS, MEASUREMENT, AND CONTROL, Vol. 119, No. 3

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Discrete time sliding mode control with reduced switching – a new reaching law approach. Andrzej Bartoszewicz. Corresponding Author. Institute of Automatic Control, Technical

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Discrete Sliding Mode Speed Control of Induction Motor ...

The Sliding Mode Control (SMC) is well known by its robustness to parameter uncertainties and external disturbances. The repetitive control (RC) is able to track or reject periodic and multi-periodic signals. This paper presents a new control strategy as a combination of a Sliding Mode approach and Repetitive Control to reject periodic and multi-periodic disturbances in the case of nonlinear ...

Sliding Mode Control for Discrete-Time Chaotic Systems ...

In this paper, a sliding mode control (SMC) of uncertain discrete singular systems with external disturbances and time-varying delays is under consideration. By use of the free weighting matrices and the Lyapunov–Krasovskii functional, a delay-dependent sufficient condition is given in strict linear matrix inequality (LMI) format to guarantee the sliding mode dynamics to be admissible ...

Discrete sliding mode control for hybrid synchronization ...

control algorithms should be discretized or the whole control system should be designed in the discrete-time domain. This paper deals with a discrete-time sliding mode control (DSMC) for induction drives. The discrete algorithms for sliding mode control of the motor speed and rotor flux are derived in detail and next tested in simulation research.

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Robust sliding mode control for uncertain discrete ...

There are a large number of sliding mode control methods for discrete-time systems (Chakrabarty & Bandyopadhyay, 2015; Zhang et al., 2008). The most commonly used discrete-time sliding mode control method is the reaching law method, which was proposed by Gao et al. (Bartoszewicz & Latosiński, 2016).

Sliding mode control for uncertain discrete-time systems ...

To attenuate bidirectional vibration, a novel discrete-time sliding mode control is proposed. This sliding mode control has time-varying gain and is combined with fuzzy sliding mode control in order to reduce the chattering of the sliding mode control. We prove that the closed loop system is uniformly stable using Lyapunov stability analysis.

Discrete-time sliding mode control for a quadrotor UAV ...

This paper presents a novel discrete-time sliding mode control (DSMC) for a general class of discrete-time chaotic systems with input nonlinearity and uncertainties. Unlike the conventional sliding mode control (SMC), the sliding surface is constructed by applying the eigenvalue assignment method to the overall system in discrete-time domain, not to the reduced system on the sliding mode in ...

Discrete sliding-mode control of a PWM inverter for ...

In control systems, sliding mode control (SMC) is a nonlinear control method that alters the dynamics of a nonlinear system by application of a discontinuous control signal (or more

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rigorously, a set-valued control signal) that forces the system to "slide" along a cross-section of the system's normal behavior. The state-feedback control law is not a continuous function of time.

Discrete-Time Sliding Mode Control with Outputs of ...

A discrete variable structure control (DVSC) with sliding vector is presented to track the velocity and acceleration command for a hypersonic cruise missile. In the design an integrator is augmented to ensure the tracking with zero steady-state errors.

New Discrete Sliding Mode Control for Nonlinear ...

The design and validation of a new fractional order (FO) reaching law for uncertain discrete-time systems is studied. A sliding mode controller is subsequently constructed by adopting the law. Unlike previous works, the presented reaching law is established on the basis of the Grünwald–Letnikov FO calculus of the switching function. A high-order disturbance compensator is integrated into ...

Discrete-time sliding mode for building structure ...

Abstract: This paper presents a discrete sliding-mode control scheme with feedforward compensation for the closed-loop regulation of the pulse-width modulated (PWM) inverter used in an uninterruptible power supply (UPS). The proposed feedforward controller can effectively improve the tracking performance of the PWM inverter. In designing the sliding-mode controller, we have taken load ...

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Disturbance Observer-Based Discrete Sliding-Mode Control ...

The goal of this paper is to improve the synchronization control performance of nonlinear teleoperation systems with system uncertainties in the presence of time delays. In view of the nonlinear discrete states of the teleoperation system in packet-switched communication networks, a new discrete sliding mode control (DSMC) strategy is performed via a new reaching law in task space.

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This work deals with sliding mode control of discrete-time systems where the outputs are defined or chosen to be of relative degrees more than one. The analysis brings forward important advancements in the direction of discrete-time sliding mode control, such as improved robustness and performance of the system. It is proved that the ultimate band about the sliding surface could be greatly ...

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